

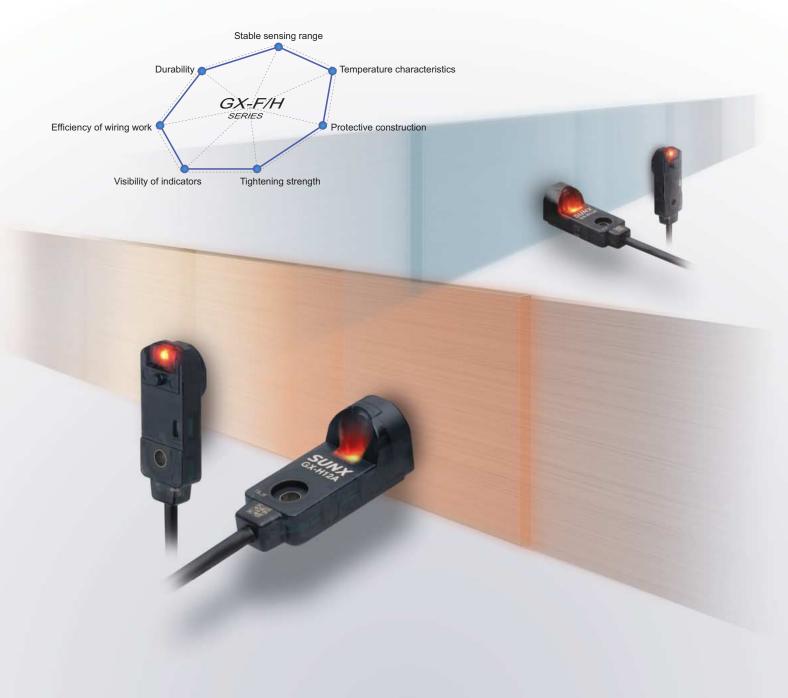


GX-F/HSERIES

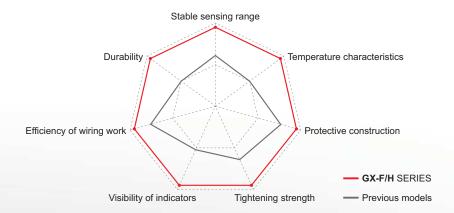


In response to the requirements of our customers

Industry No. 1* in stable sensing



^{*} Based on research conducted by SUNX as of August 2007 among equivalent rectangular inductive proximity sensors.



Use with confidence at any time and anywhere

Have you ever thought that sensing was simple, but then when you tried to use an rectangular inductive proximity sensor, the sensing was not stable? It is because SUNX is the leading manufacturer of inductive proximity sensors that we have been able to accumulate our sensor technology to develop high-precision inductive proximity sensors that can be used at any time and anywhere.

The requirements of our customers have been accommodated by basic performance which is not to be found with other manufacturers.



The industry No. 1* in accommodating to customer requirements in basic performance

* Based on research conducted by SUNX as of August 2007 among equivalent rectangular inductive proximity sensors.

Customer requirements	Answer of GX-F/H series	
We're frustrated because sensing results weren't stable. 1 And the screw mounting method makes it difficult to adjust the sensor position.	>> Industry No. 1 in stable sensing	P.3 Maximum operation distance variation: 0.4 mm 0.016 in or less Maximum operation distance: 2.5 mm 0.096 in ± 8 % (2.3 to 2.7 mm 0.091 to 0.106 in)
When the sensing position changes because of temperature variations during the morning, afternoon and nighttime, fine adjustments become very difficult to make.	>> Industry No. 1 in temperature characteristics	P.4 23 °C 73 °F 73
We want sensors that are good at withstanding vibration and shocks!	>> Industry No. 1 in durability	P.5
Are the sensors really safe to be used in places where water or oil will get on them?	>> Industry No. 1 in protective construction	P.5
We'd really like to have sensors that let you see the operating status at a glance.	>> Bright and easy-to-see indicators	P.5
If you tighten the screws too tightly, it will damage the sensors.	>> Improved tightening strength	P.6
There are too many thin wires which are very difficult to work with!	>> Greater efficiency in wiring work	P.6

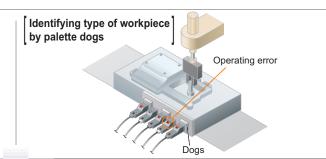
Customer requirements



We're frustrated because sensing results weren't stable. And the screw mounting method makes it difficult to adjust the sensor position.

<Have you ever had this experience?>

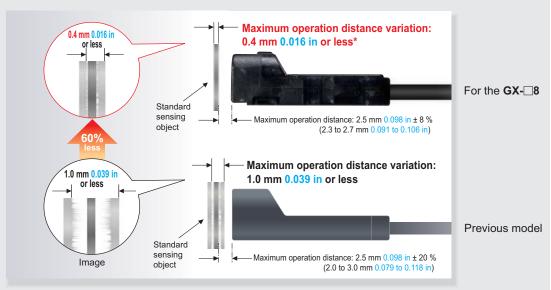
- The positions of rectangular inductive proximity sensors which are installed using screws cannot be adjusted, and so they have been designed with as short sensing ranges as possible to minimize variations caused by the sensing range.
- The sensor used as a replacement for maintenance has a longer sensing range, so that not only the dog but also the base was detected, meaning that position adjustment is necessary.



Answer of GX-F/H series

Industry No.1

Stable sensing! Variation at the maximum operation distance is within ±8 %



Thorough adjustment and control of sensing sensitivity greatly reduces individual sensor differences and variations. The work of adjusting sensor positions when using multiple sensors and when sensors have been replaced has become much easier.

* Not including temperature characteristics.
GX-□12 has a variation of 0.64 mm
0.025 in or less for a maximum operation distance of 4 mm 0.157 in



Answer of GX-F/H series

The longest stable sensing range in the industry gives you much greater flexibility.



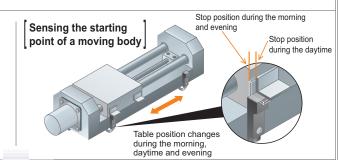
Customer requirements



When the sensing position changes because of temperature variations during the morning, afternoon and nighttime, fine adjustments become very difficult to make.

<Have you ever had this experience?>

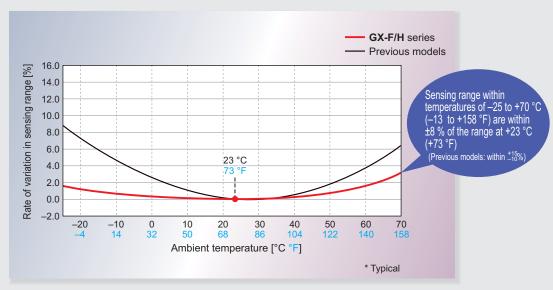
- Temperature differences between morning and nighttime or as a result of seasonal changes cause slight shifts in the sensing position.
- © Every time when the equipment is moved to a place with different weather conditions, readjustments are necessary.



Answer of GX-F/H series

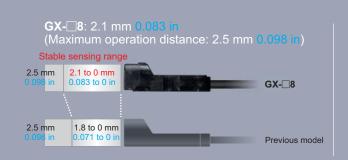
Industry No.1

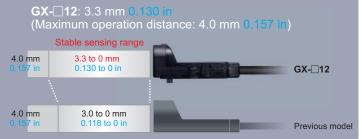
Stable sensing! Temperature characteristics vary within ±8 %



Components such as the sensor coil and core and product design have been totally revised to provide excellent temperature characteristics. Stable sensing can be obtained regardless of the time of the day or the yearly seasons.







Customer requirements

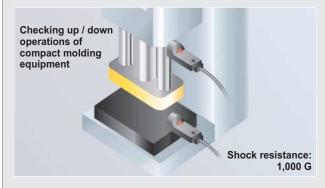


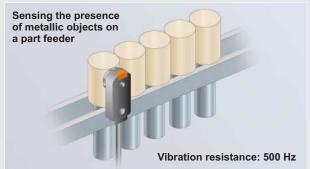
We want sensors that are good at withstanding vibration and shocks!

Answer of GX-F/H series

Industry No.1

10 times the durability! (Compared to previous models)





The new integrated construction method used provides shock resistance of $10,000 \text{ m/s}^2$ (approx. 1,000 G in X, Y and Z directions for three times each), and vibration resistance which clears durability tests of between 10 and 500 Hz (3 mm 0.118 in amplitude in X, Y and Z directions for 2 hours each). In addition, resistance to impulse noize is approx. three times greater than for previous models.



Customer requirements



Are the sensors really safe to be used in places where water or oil will get on them?

Answer of GX-F/H series

Industry No.1

Highly resistant to water or oil! IP68g* protective construction



The new integrated construction method used improves environmental resistance performance.

The IP68g prevents damage to the sensor by stopping water and oil from getting inside.

* For details, refer to the "SPECIFICATIONS" (p.8~)

Customer requirements



We'd really like to have sensors that let you see the operating status at a glance.

Answer of GX-F/H series









GX-F□







A prism with a wide field of view has been developed. This has greatly improved the visibility of the operation indicators.







If you tighten the screws too tightly, it will damage the sensors.



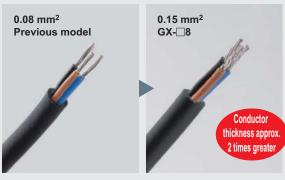




There are too many thin wires which are very difficult to work with!

Answer of GX-F/H series

Conductor thickness doubled to make wiring much easier! (GX-\subseteq 8 only)

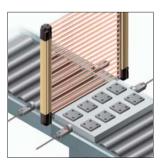


The conductor's thickness was doubled for the **GX-**—8. This makes it easier to handle and perform crimping work on the cables. In addition, the tensile strength of the crimping area has become higher.



Applications

* Maximum tightening torque for M3 screw.



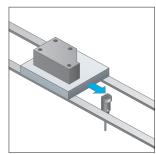
Muting control of light curtains



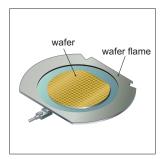
Detecting cam position



Detecting rolling coins



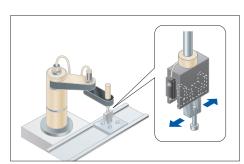
Positioning metal pallets



Detecting wafer flame



Positioning processing equipment



Checking robot finger chucks

GX-8 type

Ту	/pe	Appearance (mm in)	Sensing range (Note 1)	Model No. (Note 2)	Output	Output operation		
	ng	\sim		GX-F8A		Normally open		
	Front sensing	7.4 0.291		GX-F8AI		Normany open		
=	ont s	8 0.315 0.906		GX-F8B		Normally closed		
NPN output	Ę.			GX-F8BI	NPN open-collector	Normally closed		
PN	g	~ 🔿		GX-H8A	transistor			
2	NPI Top sensing	ensir	8.2 0.323	Maximum	Maximum	GX-H8AI		Normally open
		8 0.315 25 0.984	operation distance 2.5 mm 0.098 in	GX-H8B		Normally closed		
	ř			GX-H8BI				
	7.4 0.29 7.4 0.29 8 0.315 0.906	- 4	(0 to 2.1 mm 0 to 0.083 in)	GX-F8A-P	PNP open-collector	Normally open		
		7.4 0.291		GX-F8AI-P				
=	ont s	8 0.315 0.906	Stable sensing range	GX-F8B-P		Normally closed		
outpr	utpu Fre	0.000		GX-F8BI-P				
PNP output	б		GX-H8A-P	transistor	Namedly as a			
nsin P	sensing			GX-H8AI-P		Normally open		
	Top se	8.2 0.323		GX-H8B-P		No continue de conti		
	1	8 0.315 0.984		GX-H8BI-P		Normally closed		

Notes: 1) The maximum operation distance stands for the maximum distance for which the sensor can detect the standard sensing object.

The stable sensing range stands for the sensing range for which the sensor can stably detect the standard sensing object even if there is an ambient temperature drift and/or supply voltage fluctuation.

2) "I" in the model No. indicates a different frequency type.

GX-12 type

Ту	/ре	Appearance (mm in)	Sensing range (Note 1)	Model No. (Note 2)	Output	Output operation	
	ng	Bui Dia		GX-F12A		Normally open	
	sensing	7.1 0.280		GX-F12AI			
±	Fronts	27.8		GX-F12B		Normally closed	
outpu	Ē	0.472		GX-F12BI	NPN open-collector	Normany closed	
NPN output	g			GX-H12A	transistor	Normally open	
Z	sensing	12 0.472 Ma	Maximum operation distance GX-H12Al GX-H12B	GX-H12AI			
	Top se	27.4			Normally aloned		
	Ĕ	12 0.472		GX-H12BI		Normally closed	
	βL	(0 to 3.3 mm 0 to 0.130 in)	(0 to 3.3 mm 0 to 0.130 in)	GX-F12A-P		Normally open	
	sensing	7.1 0.280	Stable consing range	GX-F12AI-P			
+=	Front s	27.8		GX-F12B-P		Namedical	
output	0.472 1.094		GX-F12BI-P	PNP open-collector	Normally closed		
PNP o	g				GX-H12A-P	transistor	Name III
P	sensing	12 0.472		GX-H12AI-P		Normally open	
	Top se	27.4		GX-H12B-P		No. and the state of	
	ĭ	12 0.472 1.079		GX-H12BI-P		Normally closed	

Notes: 1) The maximum operation distance stands for the maximum distance for which the sensor can detect the standard sensing object. The stable sensing range stands for the sensing range for which the sensor can stably detect the standard sensing object even if there is an ambient temperature drift and/or supply voltage fluctuation.

2) "I" in the model No. indicates a different frequency type.

OPTIONS

Designation	Model No.	Description
Sensor mounting bracket	MS-GXL8-4	Mounting bracket for GX-8 type

Sensor mounting bracket

• MS-GXL8-4



1 pc. each of M3 (length: 12 mm 0.472 in) truss head screw, nut. spring washer and plain washer is attached.

SPECIFICATIONS

GX-8 type

		Туре	NPN (output	PNP output		
		Front sensing Top sensing	GX-F8A(I)	GX-F8B(I)	GX-F8A(I)-P	GX-F8B(I)-P	
Iten	n \	Top sensing	GX-H8A(I)	GX-H8B(I)	GX-H8A(I)-P	GX-H8B(I)-P	
Max. operation distance (Note 3)			2.5 mm 0.098 in ± 8 %				
Stable sensing range (Note 3)				0 to 2.1 mm	0 to 0.083 in		
Star	Standard sensing object Iron sheet 15 × 15 × t 1 mm 0.591 × 0.591 × t 0.039 in						
Hys	teresis		:	20 % or less of operation distance	ce (with standard sensing object)	
Rep	eatabil	ity	Along	sensing axis, perpendicular to s	ensing axis: 0.04 mm 0.0016 in	or less	
Sup	ply volt	tage		12 to 24 V DC ⁺¹⁰ %	Ripple P-P 10 % or less		
Curi	rent co	nsumption		15 mA	or less		
Output			Residual voltage: 1 V or le	or less (between output and 0 V)	PNP open-collector transistor • Maximum source current: 100 mA • Applied voltage: 30 V DC or less (between output an • Residual voltage: 1 V or less (at 100 mA source cur 0.4 V or less (at 16 mA source cu		
	Outpu	ut operation	Normally open	Normally closed	Normally open	Normally closed	
Max	Max. response frequency		500 Hz				
Ope	eration i	indicator	Orange LED (lights up when the output is ON)				
ą,	Prote	ction	IP68 (IEC), IP68g (JEM) (Note 4, 5)				
Environmental resistance	Ambi	ent temperature	-25 to +70 °C -13 to +158 °F, Storage: -40 to +85 °C -40 to +185 °F				
resis	Ambi	ent humidity	45 to 85 % RH, Storage: 35 to 95 % RH				
ental	Volta	ge withstandability	1,000 V AC for one min. between all supply terminals connected together and enclosure				
onme	Insula	ation resistance	$50\ \text{M}\Omega,$ or more, with $500\ \text{V}$ DC megger between all supply terminals connected together and enclosure				
invir	Vibra	tion resistance	10 to 500 Hz frequency, 3 mm 0.118 in amplitude in X, Y and Z directions for two hours each				
	Shoc	k resistance	10,000 m/s² acceleration (1,000 G approx.) in X, Y and Z directions for three times each				
	Sensing range Temperature characteristics		Over ambient temperature range –25 to +70 °C –13 to +158 °F: Within ±8 % of sensing range at +23 °C +73 °F				
variation Voltage characteristics			Within ± 2 % for $^{+10}_{-15}$ % fluctuation of the supply voltage				
Material Enclosure: PBT, Indicator part: Polyester		icator part: Polyester					
Cab	le		0.15 mm ² 3-core oil, heat and cold resistant cabtyre cable, 1 m 3.281 ft long				
Cab	le exte	nsion	Extensi	on up to total 100 m 328.084 ft i	s possible with 0.3 mm ² , or more	e, cable.	
Net	weight		F	Front sensing type: 15 g approx.	, Top sensing type: 20 g approx.		

- Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were an ambient temperature of +23 °C +73 °F.

 2) "I" in the model No. indicates a different frequency type.

 - 3) The maximum operation distance stands for the maximum distance for which the sensor can detect the standard sensing object. The stable sensing range stands for the sensing range for which the sensor can stably detect the standard sensing object even if there is an ambient temperature drift and/or supply voltage fluctuation.
 - 4) SUNX's IP68 test method
 - ① Immerse at 0 m below 0 °C +32 °F water surface and leave for 30 min. Then, immerse at 0 m below +70 °C +158 °F water surface and leave for 30 min. ② Regard the heat shock test in ① as one cycle and perform 20 cycles.

 - 3 Leave in water at a depth of 1 m 3.281 ft in water for 500 hours.
 - 4 After tests 1 to 3, insulation resistance, voltage withstandability, current consumption, and sensing ranges must meet the standard values.
 - 5) If using the sensor in an environment where cutting oil droplets splatter, the sensor may deteriorate due to added substances in the oil.

GX-12 type

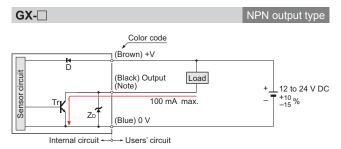
Туре			NPN (output	PNP output		
		Front sensing	GX-F12A(I)	GX-F12B(I)	GX-F12A(I)-P	GX-F12B(I)-P	
Iten	n \	Tront sensing Top sensing	GX-H12A(I)	GX-H12B(I)	GX-H12A(I)-P	GX-H12B(I)-P	
Max. operation distance (Note 3)			4.0 mm 0.157 in ± 8 %				
Stable sensing range (Note 3)				0 to 3.3 mm 0 to 0.130 in			
Standard sensing object Iron sheet 0 × 20 × t 1 mm 0.787 × 0.787 × t 0.039 in							
Hys	teresis		:	20 % or less of operation distance	ce (with standard sensing object)	
Rep	eatabil	lity	Along	sensing axis, perpendicular to s	ensing axis: 0.04 mm 0.0016 in	or less	
Sup	ply vol	tage		12 to 24 V DC ⁺¹⁰ ₋₁₅ %	Ripple P-P 10 % or less		
Curr	rent co	nsumption		15 mA	or less		
Output			Residual voltage: 1 V or le	or less (between output and 0 V)	 Residual voltage: 1 V or less (at 100 mA source curr 		
	Outp	ut operation	Normally open	Normally closed	Normally open	Normally closed	
Max	. respo	onse frequency	500 Hz				
Ope	ration	indicator	Orange LED (lights up when the output is ON)				
ø	Prote	ection	IP68 (IEC), IP68g (JEM) (Note 4, 5)				
stanc	Ambi	ent temperature	–25 to +70 °C −13 to +158 °F, Storage: −40 to +85 °C −40 to +185 °F				
Environmental resistance	Ambi	ent humidity	45 to 85 % RH, Storage: 35 to 95 % RH				
ental	Volta	ge withstandability	1,000 V AC for one min. between all supply terminals connected together and enclosure				
onme	Insula	ation resistance	$50\ M\Omega,$ or more, with $500\ V$ DC megger between all supply terminals connected together and enclosure				
Envir	Vibra	tion resistance	10 to 500 Hz frequency, 3 mm 0.118 in amplitude in X, Y and Z directions for two hours each				
ш	Shoc	k resistance	10,000 m/s ²	acceleration (1,000 G approx.)	in X, Y and Z directions for three	times each	
Sensing Temperature characteristics range		Temperature characteristics	Over ambient temperature range –25 to +70 °C –13 to +158 °F: Within ±8 % of sensing range at +23 °C +73 °F				
varia		Voltage characteristics	Within ±2 % for $^{+10}_{-15}$ % fluctuation of the supply voltage				
Material Enclosure: PBT, Indicator part: P		icator part: Polyester					
Cab	le		0.15 r	0.15 mm ² 3-core oil, heat and cold resistant cabtyre cable, 1 m 3.281 ft long			
Cab	le exte	ension	Extensi	on up to total 100 m 328.084 ft i	s possible with 0.3 mm ² , or more	e, cable.	
Net	weight		Ī	Front sensing type: 20 g approx.	, Top sensing type: 20 g approx.		
	4) 14	/horo magairament o		d procingly, the conditions would			

Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were an ambient temperature of +23 °C +73 °F.

- 2) "I" in the model No. indicates a different frequency type.
- 3) The maximum operation distance stands for the maximum distance for which the sensor can detect the standard sensing object.

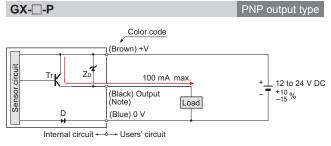
 The stable sensing range stands for the sensing range for which the sensor can stably detect the standard sensing object even if there is an ambient temperature drift and/or supply voltage fluctuation.
- 4) SUNX's IP68 test method
 - ① Immerse at 0 m below 0 °C +32 °F water surface and leave for 30 min. Then, immerse at 0 m below +70 °C +158 °F water surface and leave for 30 min.
 - $\stackrel{\frown}{\textcircled{2}}$ Regard the heat shock test in $\stackrel{\frown}{\textcircled{1}}$ as one cycle and perform 20 cycles.
 - 3 Leave in water at a depth of 1 m 3.281 ft in water for 500 hours.
- 4 After tests 1 to 3, insulation resistance, voltage withstandability, current consumption, and sensing ranges must meet the standard values.
- 5) If using the sensor in an environment where cutting oil droplets splatter, the sensor may deteriorate due to added substances in the oil.

I/O CIRCUIT DIAGRAMS



Note: The output does not incorporate a short-circuit protection circuit. Do not connect it directly to a power supply or a capacitive load.

Symbols ... D : Reverse supply polarity protection diode
Zo: Surge absorption zener diode
Tr: NPN output transistor



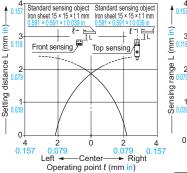
Note: The output does not incorporate a short-circuit protection circuit. Do not connect it directly to a power supply or a capacitive load.

Symbols ... D : Reverse supply polarity protection diode $Z_{\text{D}} :$ Surge absorption zener diode Tr: PNP output transistor

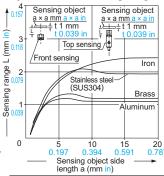
SENSING CHARACTERISTICS (TYPICAL)

GX-8 type

Sensing field



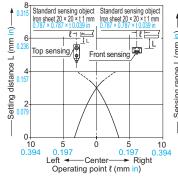
Correlation between sensing object size and sensing range



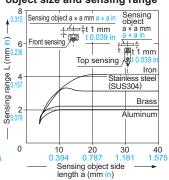
As the sensing object size becomes smaller than the standard size (iron sheet 15 \times 15 \times t 1 mm 0.591 \times 0.591 \times t 0.039 in), the sensing range shortens as shown in the left figures.

GX-12 type

Sensing field



Correlation between sensing object size and sensing range



As the sensing object size becomes smaller than the standard size (iron sheet 20 × 20 × 1 mm 0.787 × 0.787 × 10.039 in), the sensing range shortens as shown in the left figure.

PRECAUTIONS FOR PROPER USE



- Never use this product as a sensing device for personnel protection.
- In case of using sensing devices for personnel protection, use products which meet laws and standards, such as OSHA, ANSI or IEC etc., for personnel protection applicable in each region or country.

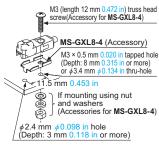
Mounting

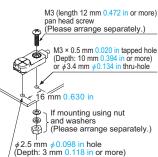
GX-8 type

Make sure to use a M3 (length: 12 mm 0.472 in or more) truss head screw. The tightening torque should be 0.7 N·m or less. (Do not use a flat head screw or a pan head screw.)



- The tightening torque should be 0.7 N·m or less.
- To mount the sensor with a nut, the mouting hole diameter should be ϕ 3.4 mm ϕ 0.134 in. Further, the hole in which the boss is inserted should be ϕ 2.5 mm ϕ 0.098 in and 3 mm 0.118 in, or more, deep.

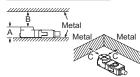




Influence of surrounding metal

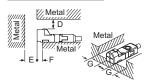
 When there is a metal near the sensor, keep the minimum separation distance specified below.

Front sensing type



	GX-F8 type	GX-F12 type
Α	7.4 mm 0.291 in	7.1 mm 0.280 in
В	8 mm 0.315 in	20 mm 0.787 in
С	3 mm 0.118 in	7 mm 0.276 in

Top sensing type



	GX-H8 type	GX-H12 type
D	4 mm 0.157 in	7 mm 0.276 in
Е	10 mm 0.394 in	20 mm 0.787 in
F	3 mm 0.118 in	3 mm 0.118 in
G	3 mm 0.118 in	3 mm 0.118 in

Mutual interference prevention

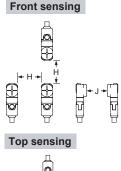
 When two or more sensors are installed in parallel or face to face, keep the minimum separation distance specified below to avoid mutual interference.

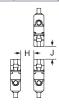
		Н	J
GX-F8□ GX-H8□	Between "I" type and non "I" type	0 mm (Note 2)	15 mm 0.591 in
	Between two "I" types or two non "I" types	20 mm 0.787 in	35 mm 1.378 in
GX-F12□	Between "I" type and non "I" type	0 mm (Note 2)	25 mm 0.984 in
GX-H12□	Between two "I" types or two non "I" types	25 mm 0.984 in	50 mm 1.969 in

Notes: 1) "I" in the model No. specifies

the different frequency type.
2) Close mounting is possible for up to two sensors.
When mounting three sensors or more at an equal spacing, align the model with "I" and the model without "I" alternately. The minimum value of dimension "H" should be as given below.

GX-8 type: 6 mm 0.236 in
GX-12 type: 6.5 mm 0.256 in





Sensing range

The sensing range is specified for the standard sensing object.
With a non-ferrous metal, the sensing range is obtained by
multiplying with the correction coefficient specified below.
Further, the sensing range also changes if the sensing object is
smaller than the standard sensing object or if the sensing object
is plated.

Correction coefficient

GX-8 type	GX-12 type		
1	1		
0.76 approx.	0.79 approx.		
0.50 approx.	0.56 approx.		
0.48 approx.	0.53 approx.		
	1 0.76 approx. 0.50 approx.		

Others

- This product has been developed / produced for industrial use only.
- The output does not incorporate a short-circuit protection circuit.
 Do not connect it directly to a power supply or a capacitive load.
- Do not use during the initial transient time (50 ms) after the power supply is switched on.
- Extension up to total 100 m 328.084 ft is possible with a 0.3 mm², or more, cable.

GX-H8□

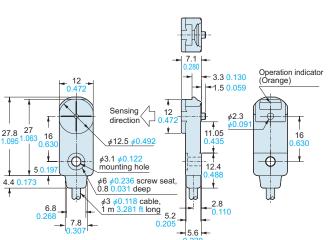
GX-H12

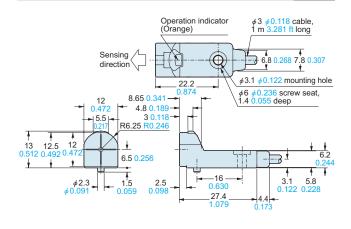
Sensor

Operation indicator (Orange) Sensing 8.55 direction 7.7 0.303 23 0.906 11.5 22.5 <u>♥</u> 6.5 φ3.1 <mark>φ</mark>0.12 9.75 mounting hole \$\phi 3 \phi 0.118 \text{ cable,} \\ 1 \text{ m 3.281 ft long} 2.65 0.03 6.3

Operation indicator (Orange) Sensing direction φ3 φ0.118 cable, 1 m 3.281 ft long 6.8 **←**2 0.079 3.7 0.146 → **-** R4.25 3.85 2.4 0.09 9 1 3-4.8 0.189 5.3 0.209

GX-F12 Sensor 8.6 0.3 4.6 0.181 2.5 -0.098 0.039





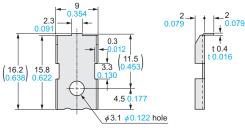
MS-GXL8-4

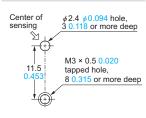
GX-F8□

Sensor mounting bracket for **GX-8 type** (optional)

Sensor

Mounting hole dimensions





Material: Stainless steel (SUS304)

1 pc. each of M3 (length 12 mm 0.472 in) truss head screw, nut, spring washer and plain washer is attached.

All information is subject to change without prior notice.



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